# Electronics / New Energy



### Metal Fabrication / General Industry



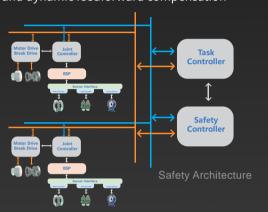
### Commercial Services / Healthcare / Research and Education



# A Powerful Yet Flexible All-Rounder

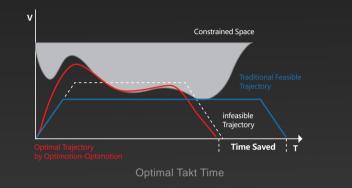
### Extreme Safety \

- Sensitivity improved by 10 times thanks to the collision detection by torque sensors
- More than 21 TÜV functional safety features, meets functional safety standards: ISO 13849-1, ISO 10218-1/PL d,
- Dual-channel redundant monitoring of sensor information and an independently certified safety controller
- The position holding accuracy is better than  $\pm 0.1$  mm when power on and off, powered by suction contracting brake and dynamic feedforward compensation



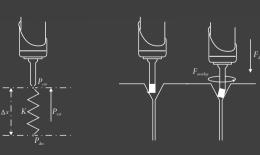
# Superior Performance \

- Cutting-edge motion control technologies for industrial robots: OptiMotion, TrueMotion, and SyncMotion
- First-class robot path accuracy supported by dynamic feedforward compensation and dynamic modeling based on over 2000 parameters
- Payload capacity increased by 20% thanks to the customized motor drive control system



### Compliant Flexibility

- Powerful yet flexible robot control based on patented unified force-position hybrid control framework
- Force control task efficiency improved by over 3 times through highly dynamic force control
   Fine grinding and precision assembly with no extension required thanks to built-in joint sensors and complete force control process kit





### Ease of Use \

- Direct teaching control with 1N based on point position and continuous trajectory
- Graphical programming interface with flowcharts enables users to get started within 1 hour
- Friendly development and open ecosystem support 100+ ecosystem extension tools of 5 categories



### Excellent Reliability \

- Motion planning based on dynamics constraints delivers high performance, overload protection, and an extended service life
- 100+ design verification experiments, 20+ factory tests, and MTBF > 80,000 h
- IP67 protection level satisfies the demands of harsh industrial applications





# Flexible Collaborative Robot



### **TECH DRIVE**

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# xMate\_

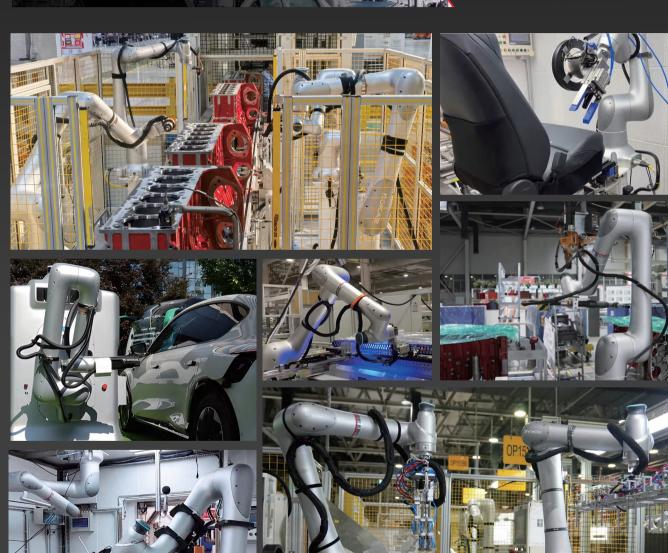
### Is changing the way all industries produce

### The xMate series is a new generation of flexible collaborative robots independently developed by ROKAE.

It features an advanced built-in torque sensors in every joint and an industrial-grade control system, delivering enhanced safety, deployment flexibility, lightweight, and ease of use in human-robot interaction.

To address diverse industry requirements, the xMate CR and SR series are launched. Leveraging cutting-edge technology and a comprehensive product portfolio, these robots expand applications into broader scenarios, becoming a reliable partner in human production and daily life.

# Automotive and Auto Parts





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	CD7 7/0 00	CD40 40/4 /	0040 00/4 /	0040 40/4 0	CD00 00/4 0	0000 05/4 0 5	ODOO 47/0 0 F	ODOF 05/0 0	ODOF / F / 4 O	000 0/07	CD / / / O	CD / E / C O
	CR7-7/0.98	CR12-12/1.4	CR12-20/1.4	CR18-18/1.0	CR20-20/1.8	CR20-25/1.8-5	CR20-17/2.0-5	CR35-35/2.2	CR35-45/1.9	SR3-3/0.7	SR4-4/0.9	SR4-5/0.9
Specifications												
Payload	7 kg	12 kg	20 kg	18 kg	20 kg	25 kg	17 kg	35 kg	45 kg	3 kg	4 kg	5 kg
Reach	988 mm	1,434 mm	1,434 mm	1,062 mm	1,798 mm	1,798 mm	2,047 mm	2,246 mm	1,947 mm	705 mm	919 mm	919 mm
Weight	About 25 kg	About 41 kg	About 41 kg	About 38 kg	About 71 kg	About 69 kg	About 71 kg	About 165 kg	About 161 kg	About 13.8 kg	About 16.5 kg	About 16.5 kg
Degrees of freedom	6	6	6	6	6	5	5	6	6	6	6	6
MTBF	> 80000 h*	> 80000h*	>80000h*	> 80000h*	> 80000h*	> 80000h*	> 80000h*			>80000h	>80000h	>80000h
Power supply	48VDC	48VDC	48VDC	48VDC	48VDC	48VDC	48VDC			48VDC	48VDC	48VDC
Programming	Direct teaching control and graphical interface	Direct teaching control and graphical interface	Direct teaching control and graphical interface	Direct teaching control and graphical interface	Graphical interface	Graphical interface	Direct teaching control and graphical interface	Direct teaching control and graphical interface	Direct teaching control and graphical interface			
Performance Taxical Dayson												
	200	F00 ···	F00 ···	C00	1000	000	C00			100	225	225
	300 w	500 w	500 w	600 w	1000 w	900 w	600 w			160 w	225 w	225 w
	300 W	500 w		600 w ole safety features including collision						Over 21 adjustable safety featu	ures including collision detection,virtu	ual walls, and collaboration mode.
Typical Power Safety Certification	300 w	500 w	Over 21 adjustab		n detection, virtual walls, and collal	boration mode. (Optional for model	ls 35kg and above)			Over 21 adjustable safety featu EN ISO 13849-1, EN ISO 1		ual walls, and collaboration mode. U CE marking requirements,
Safety	300 w  Force, x-y-z Torque, x-y-z	500 w  Force, x-y-z Torque, x-y-z	Over 21 adjustab	le safety features including collision	n detection, virtual walls, and collal	boration mode. (Optional for model	ls 35kg and above)			Over 21 adjustable safety featu EN ISO 13849-1, EN ISO 1	ures including collision detection,virtu .0218-1/ PL d, Cat. 3; ISO 15066, and El	ual walls, and collaboration mode. U CE marking requirements,
Safety Certification			Over 21 adjustab EN ISO 13849-1, EN	ble safety features including collision	n detection,virtual walls, and collal	boration mode. (Optional for model	ls 35kg and above) narking requirements			Over 21 adjustable safety featu EN ISO 13849-1, EN ISO 1 KCs ma	ures including collision detection,virtu 0218-1/ PL d, Cat. 3; ISO 15066, and El arking requirements,EAC marking requ	ual walls, and collaboration mode. U CE marking requirements, uirements

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Repeatability	±0.	02 mm	±0.03	3 mm	±0.0	)5 mm	±0.0	3 mm	±0.0	5 mm	±0.0	05 mm	±0.0	05 mm	$\pm 0.0$	5 mm	±0.0	)5 mm	±0.0	)3 mm	±0.03	3 mm	±0.03	3 mm
Motion joint	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed	d Working range	Maximum speed	Working range	Maximum spe														
Axis 1	±360°	180°/s	±360°	120°/s	±360°	90°/s	±360°	120°/s	±360°	120°/s	±360°	120°/s	±360°	120°/s	±360°	163°/s	±360°	163°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s
Axis 2	±360°	180°/s	±360°	120°/s	±360°	90°/s	±360°	120°/s	±360°	120°/s	±360°	120°/s	±360°	120°/s	±360°	163°/s	±170°	163°/s	-155° ~ +140°	180°/s	-160°~ +150°	180°/s	-160°~ +150°	180°/s
Axis 3	±360°	234°/s	±360°	180°/s	±360°	112°/s	±165°	180°/s	±170°	120°/s	±170°	120°/s	±165°	120°/s	±168°	135°/s	±168°	135°/s	-175°~ +135°	180°/s	-170°~ +140°	180°/s	-170°~ +140°	180°/s
Axis 4	±360°	240°/s	±360°	234°/s	±360°	146°/s	±360°	180°/s	±360°	180°/s	±360°	234°/s	±360°	234°/s	±360°	155°/s	±360°	155°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s
Axis 5	±360°	240°/s	±360°	240°/s	±360°	200°/s	±360°	180°/s	±360°	234°/s	±360°	234°/s	±360°	234°/s	±360°	199°/s	±360°	199°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s
Axis 6	±360°	240°/s	±360°	240°/s	±360°	200°/s	±360°	180°/s	±360°	234°/s	_		_		±360°	228°/s	±360°	228°/s	±360°	180°/s	±360°	180°/s	±360°	180°/s
Maximum speed at tool end	€3	.2 m/s	€3.0	m/s	€3.	0 m/s	€3.0	) m/s	€3.	5 m/s	€3.	5 m/s	≪4.	0 m/s	≪6.	) m/s	≪6.	0 m/s	≤1.	5 m/s	≤2.0	m/s	≤2.0	) m/s

### Physical properties

IP67	IP67	IP54
5	5	5
≤ 70 dB(A)	≤ 85 dB(A)	≤ 70 dB(A)
0°C~50°C	0°C~40°C	0°C~50°C
≤ 93% RH (non-condensing)	≤ 93% RH (non-condensing)	≤ 93% RH (non-condensing)
At any angle	At any angle	At any angle
2 Digital outputs, 2 Digital inputs, 2 Analog inputs	2 Digital outputs, 2 Digital inputs, 2 Analog inputs	2 Digital outputs, 2 Digital inputs, 2 Analog inputs
RS485(Alternative with two analog input pins, can not be used simultaneously)	RS485(Alternative with two analog input pins, can not be used simultaneously)	One 100-megabit Ethernet port with RJ45 interface on the connection base
12V/24V 1A (rated)	12V/24V 1A (rated)	(1) 12V/24V 1A (2) 5V 1.5A
	5  ≤ 70 dB(A)  0°C~50°C  ≤ 93% RH (non-condensing)  At any angle  2 Digital outputs, 2 Digital inputs, 2 Analog inputs  RS485(Alternative with two analog input pins, can not be used simultaneously)	$ 5 \\ \leqslant 70  dB(A) \\ 0^{\circ}C^{\sim}50^{\circ}C \\ 0^{\circ}C^{\sim}40^{\circ}C \\ \leqslant 93\%  RH  (non-condensing) \\ At any angle \\ 2  Digital  outputs, 2  Digital  inputs, 2  Analog  inputs \\ RS485 (Alternative with two analog input pins, can not be used simultaneously) $

1, Considering the upgrade of the product, the actual parameters of the product shall be subject to the corresponding hardware installation manual







### Contro

Controller						
Name	xMate Control Cab ( MCC )	xMate Control Cab Mix(MCCM)	LightCab			
Applicable models	CR Series models below 35kg, SR Series	CR Series models 35kg and above	SR Series			
IP rating	IP54		IP20			
Operating ambient temperature	0°C~50°	С	0°C~50°C			
Humidity	≤93% RH (Non-co	≤93% RH (Non-condensing)				
Input power	Single-phase 90V~264VAC, 47-63Hz; Single-phase 180V~264VAC, 47-63Hz (CR20 Series)	110V~260V AC, 50~60Hz	48VDC			
Dimensions	450 mm×250 mm×350 mm	480 mm×325 mm×360 mm	228.5 mm x 180 mm x 88 mm			
Weight*	About 15	kg	About 2.4 kg			
General digital IO	16 inputs and 16 outp	16 inputs and 16 outputs (standard)				
Safety IO	5 safety inputs, 4 safety outputs (a	5 safety inputs, 4 safety outputs (all dual-redundant channels)				
Communication	RS232*1; Gigabit Ethernet RJ45*1;U	RS232*1; Gigabit Ethernet RJ45*1;USB3.0*2; HDMI*1; EtherCAT*1				
Optional extension	General Digital I/O module Incremental encoder signal a	_	General Digital I/O module; Analog I/O module; Incremental encoder signal acquisition module, etc.			

<sup>\*</sup>Note: There will be some differences in the weight of the control cabinet in different configurations.







### Robot-Integrated Controller

Controller	Built-in controller							
Applicable models*	CR7,CR12,CR18,CR20 SR3,SR4							
Operator interface	Notebook/PAD/Drag Interactive Module							
Safety protection device	1 handheld enable / 1 handheld emergency stop							
Communication protocols	TCP/IP 1000Mbit, Modbus TCP, Profinet, Ethernet/IP, DeviceNet, CC-Link, CC-Link IE Field Basic							
External control interface	Highly dynamic external control; low-level force/position control; robot model library and API							
Input power	48VDC							
Base I/O ports	4 Digital outputs, 4 Digital inputs, 2 safety input, 1 safety output							
Base communication interface	1 channel Ethernet	2 channels Ethernet						
Base output power supply	24V, 1.5A	24V, 1.5A						

<sup>\*</sup>Note: Integrated controller inside the robot body is an option.



### **Teach Pendant**

reach Pendant		
Name	xPad2	
Dimensions	290 mm×170 mm×80 mm	
Weight	About 840g ( excluding cable )	
Cable length	5 m/7 m/15 m/22 m	
Display	10.1-in LCD with a resolution of 1,920×1,200	
IP rating	IP54	

<sup>2</sup>, \*Note: If you have any questions about the status of product certification, please contact the manufacturer.