Compax3M Installation Manual

Multi-axis devices

Paper version



Unterlagen / Software user guides / tools manuels / tools:

- ◆ Compax3 DVD (english, deutsch, français)
- ♦ Compax3M Installations-Handbuch deutsch
- ◆ Compax3M Installation Manual english
- ♦ Manuel technique Compax3M français

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1. Notes on the Documents Supplied

Compax3 – Installtion manual

The present manual contains the installation instructions for the associated Compax3 device series (refer to Chapter "Device Assignment").

This installation manual does contain only the basic information; for more detailed information please refer to the Help-files of the individual Compax3 device types.

Compax3 - DVD

C3 ServoManager

The enclosed self-starting* DVD contains the "C3 ServoManager" software tool for configuring, optimizing etc. Compax3.

Please use always the latest C3 ServoManager version,

Parker Integrated Engineering Tool

Furthermore, the "Parker Integrated Engineering Tool", a software tool for the project management of several Parker Motion Control products, can be found on the C3 DVD.

Several axes are managed in a common project. The Compax3 ServoManager is integrated per "Plug & Play" for each Compax3 axis. The configuration, optimization,.. take place in the same way as in an independently working C3 ServoManager.

The "C3 ServoManager" software tool is also functioning independently from the Parker Integrated Engineering Tool!

Online help system

After the installation of the ServoManager you can copy the desired Online help system with the "C3 ServoManager Help Installer" (you can select the C3 device type as well as the desired language) to your PC. The help system can be called up directly from the ServoManager. You will find the complete description of the selected device type in these online help files.

Please note that the help files are associated with defined device and software versions.

Catalogs

The catalogs supplied provide an overview of and information on the Compax3 device series.

Adobe Acrobat Reader®

For reading PDF files you need the "Adobe Acrobat Reader", a software tool which is available free of charge. and it is distributed and generally accepted throughout the world. You can also download it directly from the Adobe website at: www.adobe.com/products/acrobat.

* If your PC has not been set up accordingly, start the "start.htm" file on the CD.

1.1 C3 ServoManager

Installation of the C3 ServoManager

The Compax3 ServoManager can be installed directly from the Compax3 DVD. Click on the appropriate hyperlink or start the installation program "C3Mgr_Setup_V.... .exe" and follow the instructions.

PC requirements

Recommendation:

Operating system: MS Windows XP SP2 / MS Windows 2000 as from SP4 / (MS Vista)

Browser: MS Internet Explorer 6.x

Processor: Intel Pentium 4 / Intel Core 2 Duo / AMD Athlon class as from

>=2GHz

RAM memory: >= 1024MB

Hard disk: >= 20GB available memory

Drive: DVD drive

Monitor: Resolution 1024x768 or higher

Graphics card: on onboard graphics (for performance reasons)

Interface: USB

Minimum requirements:

Operating system: MS Windows XP SP2 / MS Windows 2000 as from SP4

Browser: MS Internet Explorer 6.x

Processor: >= 1.5GHz RAM memory: 512MB

Hard disk: 10GB available memory

Drive: DVD drive

Monitor: Resolution 1024x768 or higher

Graphics card: on onboard graphics (for performance reasons)

Interface: USB

Note:

- ◆ For the installation of the software you need administrator authorization on the target computer.
- ◆ Several applications running parallelly, reduce the performance and operability.
- especially customer applications, exchanging standard system components (drivers) in order to improve their own performance, may have a strong influence on the communication performance or even render normal use impossible.
- ◆ Operation under virtual machines such as Vware Workstation 6/ MS Virtual PC is not possible.
- ◆ Onboard graphics card solutions reduce the system performance by up to 20% and cannot be recommended.
- ◆ Operation with notebooks in current-saving mode may lead, in individual cases, to communication problems.

Connection between PC and Compax3MP

Your PC is connected to the Compax3MP connector X3 (mains module) via an USB cable (SSK33/03).

Start the Compax3 ServoManager and make the setting for the assigned interface

in the "Options Communication settings RS232/RS485..." menu.

The interface is marked as "USB Serial Port (COMx)" in the windows device manager. The no. of the COM port "x" may vary. You can find it in the PC under

system control, system, hardware, device manager, connections.

Device Selection In the menu tree under device selection you can read the device type of the

connected device (Online Device Identification) or select a device type (Device

Selection Wizard).

Configuration Then you can double click on "Configuration" to start the configuration wizard. The

wizard will lead you through all input windows of the configuration.

Contents

| 1. | Note | s on th | ne Documents Supplied | 3 |
|----|-------|---------|---|----|
| | 1.1 | C3 Ser | voManager | 4 |
| 2. | Intro | | n | |
| | 2.1 | Device | assignment | 7 |
| | 2.2 | Type s | pecification plate | 8 |
| | 2.3 | Packag | ging, transport, storage | 10 |
| | 2.4 | Safety | Instructions | 11 |
| | | 2.4.1. | General hazards | 11 |
| | | 2.4.2. | Safety-conscious working | 11 |
| | | 2.4.3. | Special safety instructions | 11 |
| | 2.5 | | nty conditions | |
| | 2.6 | Condit | ions of utilization | 14 |
| | | 2.6.1. | Conditions of utilization for CE-conform operation | |
| | | 2.6.2. | Conditions of utilization for UL certification Compax3M | 16 |
| | | 2.6.3. | Current on the mains PE (leakage current) | |
| | | 2.6.4. | Supply networks | |
| _ | 2.7 | | acturer's Declaration of Conformity | |
| 3. | Devi | | cription | |
| | 3.1 | | ation instructions Compax3M | |
| | 3.2 | Mounti | ing and dimensions | |
| | | 3.2.1. | Mounting and dimensions Compax3MP10/M050-150 | |
| | | 3.2.2. | Installation and dimensions Compax3MP20/M300 | |
| | | 3.2.3. | With upper mounting, the housing design may be different | |
| | 3.3 | | of delivery | |
| | 3.4 | | ng of the status LED - Compax3 axis controller | |
| | 3.5 | | ng of the status LED - Compax3MP (mains module) | |
| | 3.6 | • | ax3MP/Compax3M connections | |
| | | 3.6.1. | Front connector | |
| | | 3.6.2. | Connections on the device bottom | |
| | | 3.6.3. | Connections of the axis combination | |
| | | 3.6.4. | Connector and pin assignment | |
| | | 3.6.5. | Control voltage 24VDC Compax3MP (mains module) | |
| | | 3.6.6. | Mains supply Compax3MP (mains module) | |
| | | 3.6.7. | Braking resistor / temperature switch Compax3MP (mains module) | |
| | | 3.6.8. | Motor / motor brake Compax3M (axis controller) | |
| | 3.7 | 3.6.9. | Safety technology option for Compax3M (axis controller)unication interfaces | |
| | 3.7 | 3.7.1. | Communikation Compax3M | |
| | 3.8 | | interfaces | |
| | 3.0 | 3.8.1. | Resolver / feedback (connector X13) | |
| | | 3.8.2. | Analog / Encoder (plug X11) | |
| | | 3.8.3. | Digital inputs/outputs (plug X12) | |
| 4. | Tech | | data | |
| | | | , aca | |

Introduction

2. Introduction

| n this chapter you can read about: | |
|--|----|
| Device assignment | 7 |
| Type specification plate | |
| Packaging, transport, storage | 10 |
| Safety Instructions | |
| Warranty conditions | 13 |
| Conditions of utilization | 14 |
| Manufacturer's Declaration of Conformity | 19 |

2.1 Device assignment

This manual is valid for the following devices:

- ◆Compax3M050D6 + supplement
- ◆Compax3M100D6 + supplement
- ◆ Compax3M150D6 + supplement
- ◆Compax3M300D6 + supplement
- ◆ Compax3MP10D6 (mains module)
- ◆ Compax3MP20D6 (mains module)

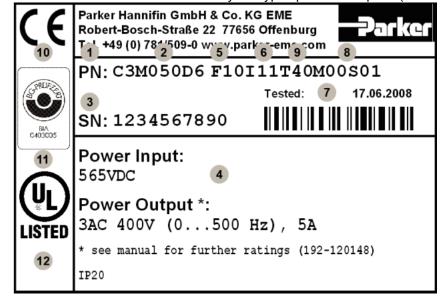
192-120148N3 October 2008 7

Introduction Multi-axis devices

2.2 Type specification plate

Compax3 - Type specification plate (Example):

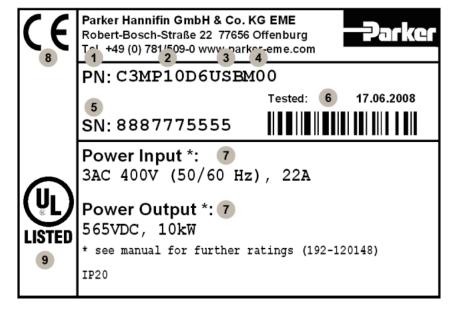
The valid device version is defined by the type specification plate (on the housing):



Explanation:

| 1 | |
|----|---|
| 1 | Type designation |
| | The complete order designation of the device (2, 5, 6, 9, 8). |
| | C3: Abbreviation for Compax3 |
| _ | \$025: Single axis device, nominal device current in 100mA (025=2.5A) |
| 2 | M050: Multi-axis device, nominal device current in 100mA (050=5A) |
| | H050: High power device, nominal device current in 1A (050=50A) |
| | D6: Designation nominal supply |
| | V2: Mains supply voltage (2=230VAC/240VAC, 4=400VAC/480VAC) |
| 3 | Unique number of the particular device |
| 3 | · |
| 1 | Nominal supply voltage Power Input: Input supply data |
| 4 | Power Output: Output data |
| | Designation of the feedback system |
| | F10: Resolver Feedback |
| 5 | F11: SinCos [®] / Single- or Multiturn |
| | F12: Feedback module for direct drives |
| | Device interface |
| | I10: Analog, step/direction and encoder input |
| | I11 / I12: Digital Inputs / Outputs and RS232 / RS485 |
| 6 | I20: Profibus DP / I21: CANopen / I22: DeviceNet / |
| | I30: Ethernet Powerlink / I31: EtherCAT |
| | C10: integrated controller C3 powerPLmC |
| | C13: integrated controller C3 powerPLmC with Profibus |
| 7 | Date of factory test |
| | Options |
| 8 | Mxx: I/O extension, HEDA |
| | Sx: optional safety technology on the C3M |
| | Technology function |
| | T10: Servo controller |
| 9 | T11: Positioning |
| | T30: Motion control programmable according to IEC61131-3 |
| | T40: Electronic cam |
| 10 | CE compliance |
| 11 | Certified safety technology (corresponding to the Logo displayed) |
| 12 | UL certification (corresponding to the Logo displayed) |
| | , , , , , , , , , , , , , , , , , , , |

Type specification plate: Compax3MP (Example):



Explanation:

| _ | | | |
|---|--|--|--|
| 1 | Type designation The complete order designation of the device (2 - 4). | | |
| 2 | C3: Abbreviation for Compax3 MPx0: Mains module 3AC 230480V, nominal power in 1kW (10=10kW) | | |
| | D6: Designation nominal supply | | |
| 3 | Configuration and parameterization interface USB: USB connection | | |
| 4 | Options Mxx: I/O extension | | |
| 5 | Unique number of the particular device | | |
| 6 | Date of factory test | | |
| 7 | Nominal supply voltage Power Input: Input supply data Power Output: Output data | | |
| 8 | CE compliance | | |
| 9 | UL certification (corresponding to the Logo displayed) | | |

Introduction Multi-axis devices

2.3 Packaging, transport, storage

Packaging material and transport



Caution!

The packaging material is inflammable, if it is disposed of improperly by burning, lethal fumes may develop.

The packaging material must be kept and reused in the case of a return shipment. Improper or faulty packaging may lead to transport damages.

Make sure to transport the drive always in a safe manner and with the aid of suitable lifting equipment (**weight** (see page 42)). Do never use the electric connections for lifting. Before the transport, a clean, level surface should be prepared to place the device on. The electric connections may not be damaged when placing the device.

First device checkup

- ◆ Check the device for signs of transport damages.
- ◆ Verify, if the indications on the type identitfications plate (see page 8) correspond to your requirements.
- ◆ Check if the consingment is complete.

Storage

If you do not wish to mount and install the device immediately, make sure to store it in a dry and clean environment. Make sure that the device is not stored near strong heat sources and that no metal chippings can get into the device.

Disposal

This product contains materials that fall under the special disposal regulation from 1996, which corresponds to the EC directory 91/689/EEC for dangerous disposal material. We recommend to dispose of the respective materials in accordance with the respectively valid environmental laws. The following table states the materials suitable for recycling and the materials which have to be disposed of separately.

| Material Option | suitable for recycling | Disposal | |
|-------------------|------------------------|----------|--|
| Metal | yes | no | |
| Plastic materials | yes | no | |
| Circuit boards | no | ves | |

Please dispose of the circuit boards according to one of the following methods:

- ◆ Burning at high temperatures (at least 1200°C) in an incineration plant licensed in accordance part A or B of the environmental protection act.
- ◆ Disposal via a technical waste dump which is allowed to take on electrolytic aluminium condensers. Do under no circumstances dump the circuit boards at a place near a normal waste dump.

Parker EME Introduction

2.4 Safety Instructions

| n this chapter you can read about: | | |
|------------------------------------|----|--|
| General hazards | 11 | |
| Safety-conscious working | 11 | |
| Special safety instructions | 11 | |

2.4.1. General hazards

General Hazards on Non-Compliance with the Safety Instructions
The device described in this manual is designed in accordance with the latest
technology and is safe in operation. Nevertheless, the device can entail certain
hazards if used improperly or for purposes other than those explicitly intended.
Electronic, moving and rotating components can

- constitute a hazard for body and life of the user, and
- ◆ cause material damage

Designated use

The device is designed for operation in electric power drive systems (VDE0160). Motion sequences can be automated with this device. Several motion sequences can be combined by interconnecting several of these devices. Mutual interlocking functions must be incorporated for this purpose.

2.4.2. Safety-conscious working

This device may be operated only by qualified personnel.

Qualified personnel in the sense of these operating instructions consists of:

- ◆ Persons who, by virtue to their training, experience and instruction, and their knowledge of pertinent norms, specifications, accident prevention regulations and operational relationships, have been authorized by the officer responsible for the safety of the system to perform the required task and in the process are capable of recognizing potential hazards and avoiding them (definition of technical personnel according to VDE105 or IEC364),
- Persons who have a knowledge of first-aid techniques and the local emergency rescue services.
- Persons who have read and will observe the safety instructions.
- ◆ Those who have read and observe the manual or help (or the sections pertinent to the work to be carried out).

This applies to all work relating to setting up, commissioning, configuring, programming, modifying the conditions of utilization and operating modes, and to maintenance work.

This manual and the help information must be available close to the device during the performance of all tasks.

2.4.3. Special safety instructions

- ◆ Check the correct association of the device and its documentation.
- ◆ Never detach electrical connections while voltage is applied to them.
- Safety devices must be provided to prevent human contact with moving or rotating parts.
- ◆ Make sure that the device is operated only when it is in perfect condition.
- ◆ Implement and activate the stipulated safety functions and devices.
- Operate the device only with the housing closed.

Introduction Multi-axis devices

- Make sure that all axes are sufficiently fixed.
- Attention during configuration downloads with master slave couplings (electronic gear, cam)
 Deactivate the drive before starting the configuration download: Master and Slave axis
- ◆ Check that all live terminals are secured against contact. Fatal voltage levels of to 850V occur.
- ◆ Do not bypass power direct current



Warning!

Due to movable machine parts and high voltages, the device can pose a lethal danger. Danger of electric shock in the case of non-respect of the following instructions. The device corresponds to DIN EN 61800-3, i.e. it is subject to limited sale. The device can emit disturbances in certain local environments. In this case, the user is liable to take suitable measures.

- ◆ The device must be permanently grounded due to high earth leakage currents.
- ◆ The drive motor must be grounded with a suitable protective lead.
- ◆ The devices are equipped with high voltage DC condensers. Before removing the protective cover, the discharging time must be awaited. After switching off the energy, it may take up to 5 minutes to discharge the capacitors. Danger of electric shock in case of non respect.
- ◆ Before you can work on the device, the supply voltage must be switched off at the L1, L2 and L3 clamps. Wait at least 3 minutes so that the power direct current may sink to a secure value (<50V). Check with the aid of a voltmeter, if the voltage at the DC+ and DC- clamps has fallen to a value below 50V (not possible on the Compax3M).
- ◆ Do never perform resistance tests with elevated voltages (over 690V) on the wiring without separating the circuit to be tested from the drive.
- ◆ In the event of a device exchange it is absolutely necessary to transfer the configuration determining the correct operation of the drive to the device, before the device is put into operation.
- ◆ The device contains electrostatically sensitive components. Please heed the electrostatic protection measures while working at/with the device as well as during installation and maintenance.



Attention - hot surface!

The heat dissipator can reach very high temperatures (>70°C)

Protective covers



Caution!

The user is responsible for protective covers and/or additional safety measures in order to prevent damages to persons and electric accidents.

Parker EME Introduction

2.5 Warranty conditions

- ◆ The device must not be opened.
- Do not make any modifications to the device, except for those described in the manual.
- Make connections to the inputs, outputs and interfaces only in the manner described in the manual.
- ◆ Fix the devices according to the mounting instructions.

 We cannot provide any guarantee for any other mounting methods.

Note on exchange of options

Compax3 options must be exchanged in the factory to ensure hardware and software compatibility.

- ◆ When installing the device, make sure the heat dissipators of the device receive sufficient air and respect the recommended mounting distances of the devices with integrated ventilator fans in order to ensure free circulation of the cooling air.
- ◆ Make sure that the mounting plate is not exposed to external temperature influences.

Introduction Multi-axis devices

2.6 Conditions of utilization

| In this chapter you can read about: | |
|---|----|
| Conditions of utilization for CE-conform operation | 14 |
| Conditions of utilization for UL certification Compax3M | |
| Current on the mains PE (leakage current) | 17 |
| Supply networks | |

2.6.1. Conditions of utilization for CE-conform operation

- Industry and trade -

The EC guidelines for electromagnetic compatibility 2006/95/EC and for electrical operating devices for utilization within certain voltage limits 2004/108/EC are fulfilled when the following boundary conditions are observed:

Operation of the devices only in the condition in which they were delivered, i.e. with all housing panels.

In order to ensure contact protection, all mating plugs must be present on the device connections even if they are not wired.

Mains filter:

A mains filter is required in the mains input line if the motor cable exceeds a certain length. Filtering can be provided centrally at the plant mains input or separately at the mains input to each axis combination.

<u>Use of the devices in the industrial area (limit values class C3 in accordance with EN 61800-3)</u>

The following mains filters are available for independent utilization:

| Device: Compax3 | Order No.: | Condition: |
|-----------------|------------|----------------------------------|
| MP10 | NFI03/01 | Reference axis combination 6x10m |
| MP10 | NFI03/02 | Reference axis combination 6x50m |
| MP20 | NFI03/03 | Reference axis combination 6x50m |

Connection length: Connection between mains filter and device:

unshielded: < 0.5m

shielded < 5m (fully shielded on ground – e.g. ground of control cabinet)

Motor and Feedback cable:

Operation of the devices only with motor and feedback cables whose plugs contain a special full surface area screening.

Requirements for Compax3M motor cable

<80m per axis (the cable must not be rolled up!)

The entire length of the motor cable per axis combination may not exceed 300m. A motor output filter is required for motor cables >20m.

- ◆MDR01/04 (max. 6.3A rated motor current)
- ◆MDR01/01 (max. 16A rated motor current)
- ◆MDR01/02 (max. 30A rated motor current)

Parker EME Introduction

Shielding connection of the motor cable

The cable should be fully screened and connected to the Compax3 housing. We offer a special Shield connecting terminal as accessory item (ZBH./...). The shield of the cable must also be connected with the motor housing. The fixing

(via plug or screw in the terminal box) depends on the motor type.

Requirements for Compax3M encoder cable:

< 80m

Requirements for other cables

Corresponding to the specifications of the terminal clamp with a temperature range of up to 60°C.

Motors: Operation with standard motors.

Control: Use only with aligned controller (to avoid control loop oscillation).

Grounding: Connect the filter housing and the Compax3 to the cabinet frame, making sure that

the contact area is adequate and that the connection has low resistance and low

inductance.

Never mount the filter housing and the device on paint-coated surfaces!

Cable installation: Signal lines and power lines should be installed as far apart as possible.

Signal leads should never pass close to excessive sources of interference (motors,

transformers, contactors etc.).

Accessories: Make sure to use only the accessories recommended by Parker

Connect all cable shields at both ends, ensuring large contact areas!

Warning:

This is a product in the restricted sales distribution class according to EN 61800-3. In a domestic area this product can cause radio frequency disturbance, in which case the user may be required to implement appropriate remedial measures.

192-120148N3 October 2008 15

Introduction Multi-axis devices

2.6.2. Conditions of utilization for UL certification Compax3M

UL certifiction for Compax3M

| conform to UL: | ◆according to UL508C |
|----------------|------------------------|
| Certified | ◆ E-File_No.: E235 342 |

The UL certification is documented by a "UL" logo on the device (type specification plate).



Conditions of utilization

- ◆ The devices are only to be installed in a degree of contamination 2 environment (maximum).
- ◆ The devices must be appropriately protected (e.g. by a switching cabinet).
- ◆ Tightening torque of the field wiring terminals (green Phoenix plugs)

| Device | X40: Braking Resistor | X41: Mains connector | X9: 24VDC |
|--------|-----------------------|----------------------|--------------------|
| C3MP10 | 0.5 (4.43Lb.in) | 1.2Nm (10.62Lb.in) | 1.2Nm (10.62Lb.in) |
| C3MP20 | 0.5 (4.43Lb.in) | 1.7Nm (15Lb.in) | 1.2Nm (10.62Lb.in) |

| Device | X43: Motor connector | X15: Temperature monitoring |
|------------|----------------------|-----------------------------|
| C3M050-150 | 0.5 (4.43Lb.in) | 0.22Nm (1.95Lb.in) |
| C3M300 | 1.2Nm (10.62Lb.in) | 0.22Nm (1.95Lb.in) |

- ◆ Temperature rating of field installed conductors shall be at least 60°C Use copper lines only. Please use the cables described in the accessories chapter; they do have a temperature rating of at least 60°C
- ◆ Maximum Surrounding Air Temperature: 40°C.
- ◆ Suitable for use on a circuit capable of delivering not more than 5000 rms symmetrical amperes and 480 volts maximum.



Caution!

Risk of Electric Shock.

Discharge time of the bus capacitator is approx. 5 minutes.

- ◆ The drive provides internal motor overload protection.
 This must be set so that 200% of the nominal motor current are not exceeded.
- ◆ Cable cross-sections
 - Mains input: corresponding to the recommended fuses.
 - Motor cable: corresponding to the nominal output currents (see on page 43)
- ◆ Maximum cross-section limited by the terminals mm² / AWG

Line cross-sections of the power connections (on the device bottoms)

| Compax3 device: | Cross-section: Minimum Maximum [mm² with contactor | |
|---|--|--|
| | sleeve] | |
| M050, M100, M150 0,25 4 (AWG: 23 11) | | |
| M300 0,5 6 (AWG: 20 10) | | |
| MP10 Mains supply: 0,5 6 (AWG: 20 10) | | |
| Braking resistor: 0,25 4 (AWG: 23 11) | | |
| MP20 Mains supply: 0,5 16 (AWG: 20 6) | | |
| | Braking resistor: 0,25 4 (AWG: 23 11) | |

Parker EME Introduction

2.6.3. Current on the mains PE (leakage current)



Caution!

This product can cause a direct current in the protective lead. If a residual current device (RCD) is used for protection in the event of direct or indirect contact, only a type B (all current sensitive) RCD is permitted on the current supply side of this product . On the other hand a different protective measure must be taken, such as for example separation from the environment by double or enforced insulation or separation from the supply network by a transformer.

Please heed the connection instructions of the RCD supplier.

Mains filters do have high leakage currents due to their internal capacity. An internal mains filter is usually integrated into the Compax3 servo controllers. Additional leakage currents are caused by the capacities of the motor cable and of the motor windings. Due to the high clock frequency of the power output stage, the leakage currents do have high-frequency components. Please check if the FI protection switch is suitable for the individual application.

If an external mains filter is used, an additional leakage current will be produced. The figure of the leakage current depends on the following factors:

- ◆Length and properties of the motor cable
- Switching frequency
- Operation with or without external mains filter
- ◆ Motor cable with or without shield network
- Motor housing grounding (how and where)

Remark:

- ◆The leakage current is important with respect to the handling and usage safety of the device.
- ◆ A pulsing leakage current occurs if the supply voltage is switched on.

Please note:

The device must be operated with effective grounding connection, which must comply with the local regulations for high leakage currents (>3.5mA). Due to the high leakage currents it is not adviseable to operate the servo controller with an earth leakage circuit breaker.

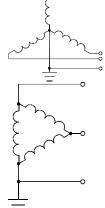
Introduction Multi-axis devices

2.6.4. Supply networks

The Compax3 servo controller series is designed for fixed connection to TN networks (TN-C, TN-C-S or TN-S). Please note that the line-earth voltage may not exceed 300VAC.

◆ When grounding the neutral conductor, mains voltages of up to 480VAC are permitted.

 When grounding an external conductor (delta mains, two-phase mains), mains voltages (external conductor voltages) of up to 300VAC are permitted.



Servo controllers which are to be connected to an IT network must be provided with a separating transformer. Then the Compax3 device is operated locally like in a TN network. The secondary sided center of the separating transformer must be grounded and connected to the PE connector of the Compax3.

Parker EME Introduction

2.7 Manufacturer's Declaration of Conformity

As defined by the EC Electromagnetic Compatibility (EMC) Directive 2004/108/EU and

the EC Directive relating to electrical equipment designed for use within

certain voltage limits (Low Voltage Directive) 2006/95/EU

We (the manufacturer)

Parker Hannifin GmbH & Co. KG

hereby declare that the designated product

Device type: Intelligent servo drives

Device models:

C3MxxxD6FxxIxxTxxMxxSxAxx

C3MPxxD6xxxMxxAxx

is, by virtue of its design concept and construction, and with reference to the version which we have put into circulation, fully compliant with the following standards or standard-related documentation.

Applied harmonized Standards, in particular:

Electromagnetic Compatibility

EN 61 800-3 EMC product standard for adjustable speed electrical power

drive systems including specific test methods

Safety

EN 61 800-5-1 Safety requirements for adjustable speed electrical power

drive systems

Caution!

The present Manufacturer's Declaration of Conformity is valid only if the master conditions for operation described in the "Conditions of Use" section have been met.

If there are any deviations or modifications to the product, this declaration shall cease to apply.

3. Device description

| n this chapter you can read about: | |
|---|----|
| nstallation instructions Compax3M | 20 |
| Mounting and dimensions | 22 |
| State of delivery | 24 |
| Meaning of the status LEDs - Compax3 axis controller | 24 |
| Meaning of the status LEDs - Compax3MP (mains module) | 25 |
| Compax3MP/Compax3M connections | 26 |
| Communication interfaces | 37 |
| Signal interfaces | 39 |

3.1 Installation instructions Compax3M

General introductory notes

- ◆ Operation of the Compax3M multi-axis combination is only possible in connection iwth a Compax3MP (mains module).
- ◆ Axis controllers are aligned at the right of the mains module.
- ◆ Alignment within the multi-axis combination sorted by power (with the same device types according to device utilization), the axis controller with the highest power directly at the right of the mains module. e.g. first the device type with high utilization, at the right of this the same device type with a lower utilization.
- ◆ Max. 15 Compax3M (axis controllers) per Compax3MP (mains module) are permitted (please respect the total capacity of max. 2400µF).
- ◆ The continuation of the current rail connection outside the axis combination is not permitted and will lead to a loss of the CE and UL approbation.
- ◆ External components **may not** be connected to the rail system.

Required tools:

- ◆Allen key M5 for fixing the devices in the control cabinet.
- ◆ Crosstip screwdriver M4 for connection rails of the DC rail modules.
- ◆ Crosstip screwdriver M5 for grounding screw of the device.
- ◆ Flat-bladed screwdriver 0.4x2.5 / 0.6x3.5 / 1.0x4.0 for wiring and mounting of the phenix clamps.

Order of installation

- Fixing the devices in the control cabinet.
 - Predrilling the mounting plate in the control cabinet according to the specifications. Dimensions (see page 22). Fit M5 screws loosely in the bores.
 - Fit device on the upper screws and place on lower screw. Tighten screws of all devices. The tightening torque depends on the screw type (e.g. 5.9Nm for M5 screw DIN 912 8.8).
- Connecting the internal supply voltages.
 The Compax3M axis controllers are connected to the supply voltages via rail modules. Details (see page 28).
 - Deblocking the yellow protective cover with a flat-bladed screwdriver on the upper surface (click mechanism). Remove the closing devices (contact protection) that are not required from between the devices.
 - Connecting the rail modules, beginning with the mains module. For this, loosen crosshead screws (5 screws at the right in the mains module, all 10 screws in the next axis controller), push the rails one after the other against to the left and tighten screws. Proceed accordingly for all adjacent axis controllers in the combination. Max. tightening torque: 1.5Nm.
 - Close all protective covers. The protective covers must latch audibly.

Please Note

Insufficiently fixed screw connections of the DC power voltage rails may lead to the destruction of the devices.

Protective covers



Caution - Risk of Electric Shock!

In order to secure the contact protection against the alive rails, it is absolutely necessary to respect the following:

- Insert the yellow plastic device at the left or right of the rails. Make sure that the yellow plastic device is placed at the left of the first device and at the right of the last device in the combination and have not been removed.
- Setup of the devices only with closed protective covers.
- ◆ Connect protective earth to mains module (M5 crossheadscrew on front of device bottom).
- ◆ Connecting the internal communication. **Details** (see page 37).
- ◆ Connecting the signal and fieldbus connectors. **Details** (see page 39).
- ◆ Connection of mains power supply **Details** (see page 31) braking resistor **Details** (see page 33) and Motor **Details** (see page 34).
- ◆ Connecting the configuration interface to the PC. Details (see page 37).

3.2 Mounting and dimensions

Ventilation:

During operation, the device radiates heat (power loss). Please provide for a sufficient mounting distance below and above the device in order to ensure free circulation of the cooling air. Please do also respect the recommended distances of other devices. Make sure that the mounting plate is not exhibited to other temperature influences than that of the devices mounted on this very plate. The devices must be mounted vertically on a level surface. Make sure that all devices are sufficiently fixed.

3.2.1. Mounting and dimensions Compax3MP10/M050-150

Compaxa3MP and Compax3M are force-ventilated via a ventilator fan fixed to the lower part of the heat dissipator!

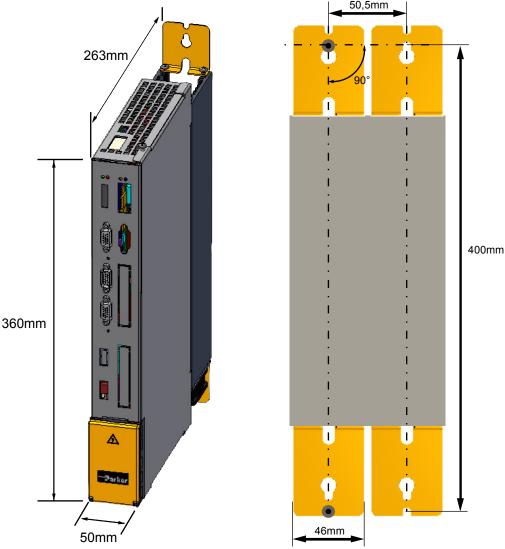
Mounting spacing: At the top and below: at least 100mm

Information on

| C3MP (mains module) | C3M (axis) |
|---------------------|------------|
| C3MP10D6 | C3M050D6 |
| | C3M100D6 |
| | C3M150D6 |

Mounting:

2 socket head screws M5



Tolerances: DIN ISO 2768-f

22

Parker EME Device description

3.2.2. Installation and dimensions Compax3MP20/M300

 Information on
 C3MP (mains module)
 C3M (axis)

 C3MP20D6
 C3M300D6

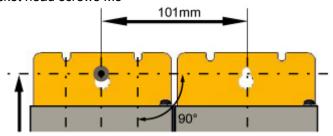
Tolerances: DIN ISO 2768-f

Mounting: 4 socket head screws M5 101mm 50,5mm 263mm 400mm 360mm 96mm 100mm

3.2.3. With upper mounting, the housing design may be different

Mounting:

3 socket head screws M5



3.3 State of delivery

Compax3 is delivered without configuration!

After switching on the 25VDC supply, the red LED is flashing while the green LED is dark

Please configure the device with the help of the Windows-Software "Compax3 – ServoManager"!

3.4 Meaning of the status LED - Compax3 axis controller

| Device status LEDs | Right LED (red) | Left LED (green) |
|--|----------------------|------------------|
| Voltages missing | off | off |
| During the booting sequence | alternately flashing | |
| No configuration present. | Flashes slowly | off |
| SinCos [®] feedback not detected. | | |
| Compax3 IEC61131-3 program not compatible with Compax3 Firmware. | | |
| no Compax3 IEC61131-3 program | | |
| For F12: Hall signals invalid. | | |
| Axis without current excitation | off | Flashes slowly |
| Power supplied to axis; commutation calibration running | off | Flashes quickly |
| Axis with current excitation | off | on |
| Axis in fault status / fault present / axis energized (error reaction 1) | Flashes quickly | on |
| Axis in fault status / fault present / axis deenergized (error reaction 2) | on | off |
| Compax3 faulty: Please contact us. | on | on |

Parker EME Device description

3.5 Meaning of the status LED - Compax3MP (mains module)

| C3MP Status LEDs | Left LED (green) | Right LED (red) |
|---|------------------|-----------------|
| Control voltage 24 VDC iss missing** | off | off |
| Error of mains module* | off | on |
| DC power voltage is built up | - | Flashes quickly |
| Phase failure / mains power supply undervoltage | on | Flashes slowly |
| Address assignment CPU active | Flashes quickly | - |
| Address assignment CPU completed | Flashes slowly | - |
| C3MPxx Ready - State | on | off |
| Incorrect wiring of internal communication X30/31 | Flashes slowly | Flashes quickly |

^{*}can be read out in each axis controller



Caution!

When the control voltage is missing there is no indication whether or not high voltage supply is available.

3.6 Compax3MP/Compax3M connections

| In this chapter you can read about: | |
|--|----|
| Front connector | 26 |
| Connections on the device bottom | 27 |
| Connections of the axis combination | 28 |
| Connector and pin assignment | 29 |
| Control voltage 24VDC Compax3MP (mains module) | 31 |
| Mains supply Compax3MP (mains module) | 31 |
| Braking resistor / temperature switch Compax3MP (mains module) | 33 |
| Motor / motor brake Compax3M (axis controller) | 34 |
| Safety technology option for Compax3M (axis controller) | 36 |

3.6.1. Front connector



| MP | Power module |
|------|---|
| LED1 | Status LEDs Mains module |
| S1 | Basic address |
| X3 | Configuraiton interface (USB) |
| X9 | Supply voltage 24VDC |
| М | Axis controller |
| LED2 | Status LEDs of the axis |
| S10 | Function |
| X11 | Analogue/Encoder |
| X12 | Inputs/Outputs |
| X13 | Motor position feedback |
| X14 | Safety technology (option) |
| X15 | Motor temperature monitoring |
| | |
| LED3 | HEDA LEDs |
| X20 | HEDA in (Option) |
| X21 | HEDA out (Option) |
| X22 | Inputs Outputs (Option M10/12) |
| X23 | Bus (option) connector type depends on the bus system! |
| X24 | Bus (option) depends on the bus system! |
| LED4 | Bus LEDs |
| S24 | bus settings |
| | |
| 1 | Behind the yellow protective covers you can find the rails for the supply voltage connection. Supply voltage 24VDC |
| | , |
| | DC power voltage supply |

3.6.2. Connections on the device bottom



Caution - Risk of Electric Shock!

Always switch devices off before wiring them! Dangerous voltages are still present until 5 minutes after switching off the power supply.



Caution!

When the control voltage is missing there is no indication whether or not high voltage supply is available.



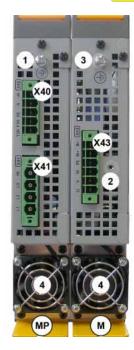
Attention - PE connection!

The PE connection is made with 10mm² via a grounding screw at the bottom of the device.



Attention - hot surface!

The heat dissipator can reach very high temperatures (>70°C)



| MP | Power module |
|-----|---|
| X40 | Braking Resistor |
| X41 | Mains supply VAC/PE |
| 1 | Central ground connection for the axis combination, |
| | with 10mm ² to the ground screw on the housing. |
| 4 | Fan* |
| | |
| M | Axis controller |
| X43 | Motor / Brake |
| 2 | Fixing for motor shield clamp |
| 4 | Fan* |
| 3 | optinally, the axis controller features a ground screw on the housing, if the grounding is not possible via the back plate. |

^{*} is internally supplied.

Line cross-sections of the power connections (on the device bottoms)

| Compax3 device: | Cross-section: Minimum Maximum [mm² with contactor | | |
|------------------|--|--|--|
| | sleeve] | | |
| M050, M100, M150 | 0,25 4 (AWG: 23 11) | | |
| M300 | 0,5 6 (AWG: 20 10) | | |
| MP10 | Mains supply: 0,5 6 (AWG: 20 10) | | |
| | Braking resistor: 0,25 4 (AWG: 23 11) | | |
| MP20 | Mains supply: 0,5 16 (AWG: 20 6) | | |
| | Braking resistor: 0,25 4 (AWG: 23 11) | | |

3.6.3. Connections of the axis combination

The Compax3M axis controllers are connected to the supply voltages via rails.

- Supply voltage 24VDC
- ◆DC power voltage supply

The rails can be found behind the yellow protective covers. In order to connect the rails of the devices, you may have to remove the yellow plastic device inserted at the side.

CAUTION: Risk of Electric Shock



Caution - Risk of Electric Shock!

Please respect before opening:



- ◆ Warning! Risk of electric shock, disconnect Power Before Removing Cover.
- ◆ Caution! Risk of Electric Shock! Energy for 5 minutes after "Power Off"!



Caution - Risk of Electric Shock!

Always switch devices off before wiring them!

Dangerous voltages are still present until 5 minutes after switching off the power supply.



Caution!

When the control voltage is missing there is no indication whether or not high voltage supply is available.

Protective covers



Caution - Risk of Electric Shock!

In order to secure the contact protection against the alive rails, it is absolutely necessary to respect the following:

- ◆ Insert the yellow plastic device at the left or right of the rails.
 Make sure that the yellow plastic device is placed at the left of the first device and at the right of the last device in the combination and have not been removed.
- ◆ Setup of the devices only with closed protective covers.

Parker EME Device description



- 1 24VDC
- 2 Gnd 24 V
- 3 -HV DC
- 4 PE
- 5 +HV DC

Note:

External components **may not** be connected to the rail system.

Protective covers

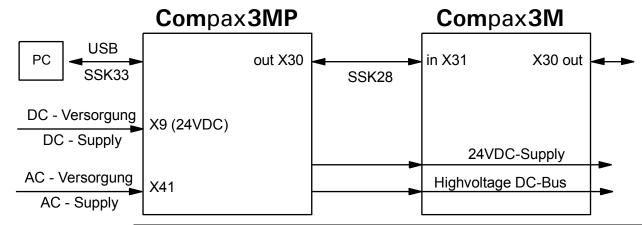


Caution!

The user is responsible for protective covers and/or additional safety measures in order to prevent damages to persons and electric accidents.

3.6.4. Connector and pin assignment

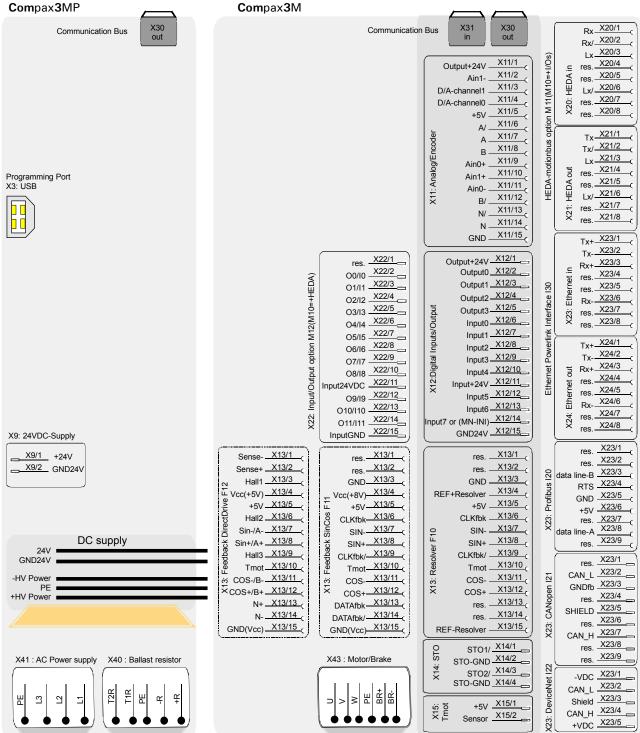
Overview:



Maximum no. of C3M axes in a combination: 15 axes (max. 2400µF).

Further information on the assignment of the plug mounted at the particular device can be found below!

In detail: The fitting of the different plugs depends on the extension level of Compax3. In part, the assignment depends on the Compax3 option implemented.



Protective covers



Caution!

The user is responsible for protective covers and/or additional safety measures in order to prevent damages to persons and electric accidents.

3.6.5. Control voltage 24VDC Compax3MP (mains module)

connector X9



| PIN | Designation |
|-----|-------------|
| 1 | +24V |
| 2 | Gnd 24 V |

Line cross sections:

minimum: 0.5mm² with contactor sleeve maximum: 6mm² with contactor sleeve

(AWG: 20 ... 10)

Control voltage 24VDC Compax3MP / Compax3M

| Device type | Compax3MP / Compax3M |
|--|--|
| Voltage range | 21 - 27VDC |
| Mains module | with switch-on current limitation, due to capacitive load |
| Fuse | MCB miniature circuit breaker or "delayed action fuse", due to capacitive load |
| Current drain of the device | C3MP10D6: 0,2A C3MP20D6: 0.3A |
| Total current drain | C3M050D6: 0,85A C3M100D6: 0.85A C3M150D6: 0.85A C3M300D6: 1.0 A + Total load of the digital outputs + current for the motor holding brake |
| Ripple | 0.5Vpp |
| Requirement according to safe extra low voltage (SELV) | yes |
| Short-circuit proof | conditional (each device internally protected with 3.15AT) |

3.6.6. Mains supply Compax3MP (mains module)

Device protection

By cyclically switching on and off the power voltage, the input current limitation can be overloaded, which may cause damage to the device.

Wait at least one minute between two switching on processes!

Connector X41



| PIN | Designation |
|-----|-------------|
| PE | |
| L3 | |
| L2 | |
| L1 | |

Mains connection Compax3MP10D6

| Device type Compax3MP10 | 230V | 400V | 480V |
|--|---|------------------------|------------------------|
| Supply voltage | 230VAC ±10% 50-60Hz | 400VAC ±10% 50-60Hz | 480VAC ±10% 50-60Hz |
| Rated voltage | 3AC 230V | 3AC 400V | 3AC 480V |
| Input current | 22Aeff | 22Aeff | 18Arms |
| Output voltage | 325VDC ±10% | 565VDC ±10% | 680VDC ±10% |
| Output power | 6kW | 10 kW | 10 kW |
| | Measure for line and device protection: | | |
| Maximum fuse rating per device (=short circuit rating) | MCB miniature circuit breaker 25A according to UL category DIVQ Recommendation: (ABB) S203UP-K 25(480VAC) | | |

Mains connection Compax3MP20D6

| Device type Compax3MP20 | 230V | 400V | 480V |
|--|---|------------------------|------------------------|
| Supply voltage | 230VAC ±10% 50-60Hz | 400VAC ±10% 50-60Hz | 480VAC ±10% 50-60Hz |
| Rated voltage | 3AC 230V | 3AC 400V | 3AC 480V |
| Input current | 44Arms | 44Arms | 35Arms |
| Output voltage | 325VDC ±10% | 565VDC ±10% | 680VDC ±10% |
| Output power | 12kW | 20kW | 20kW |
| Maximum fuse rating per device (=short circuit rating) 2 circuit breakers in line are required | Measure for line protection: MCB with a rating of 50A / 4xxVAC (depending on the input voltage)Recommendation: Recommendation: (ABB) S203U-K50 (440VAC) Measure for device protection: | | |
| | Fuses 80A / 660VAC per supply leg according to UL category JFHR2 Bussmann 170M1366, 170M1566D | | |

Caution!

The Compax3MPxxD6 devices must only be operated with three phases!



Caution - Risk of Electric Shock!

Always switch devices off before wiring them! Dangerous voltages are still present until 5 minutes after switching off the power supply.

Parker EME Device description

3.6.7. Braking resistor / temperature switch Compax3MP (mains module)

The energy generated during braking operation must be dissipated via a braking resistor.

Connector X40



| PIN | Description | | |
|-----|--------------------|------------------------------|--|
| +R | + Braking resistor | no short-circuit protection! | |
| -R | - Braking resistor | · | |
| PE | PE | | |
| T1R | Temperature Switch | | |
| T2R | Temperature Switch | | |

Braking operation Compax3MPxxD6 (mains module)

| Device type Compax3 | MP10 | MP20 |
|----------------------------------|--|---|
| Capacitance / storable energy | 550µF/ 92Ws at 400V 53Ws at 480V | 1175µF/ 197Ws at 400V 114Ws at 480V |
| Minimum braking- resistance | 27Ω | 15Ω |
| Recommended nominal power rating | 500 1500W | 500 3500W |
| Pulse power rating for 1s | 22kW | 40kW |
| Maximum permissible peak current | 13A | 15A |

Braking operation Compax3MxxxD6 (axis controller)

| Device type Compax3 | M050 | M100 | M150 | M300 |
|------------------------|--------------|--------------|--------------|--------------|
| Capacitance / | 110µF/ | 220µF/ | 220µF/ | 440µF/ |
| storable energy | 18Ws at 400V | 37Ws at 400V | 37Ws at 400V | 74Ws at 400V |
| | 10Ws at 480V | 21Ws at 480V | 21Ws at 480V | 42Ws at 480V |

Maximum capacity in the axis combination: 2400µF

Connection of a braking resistor on Compax3MP (mains module)

Mimimum line cross section:1.5mm²Maximum line length:2mMaximum intermediate circuit voltage:810VDCSwitch-on threshold:780VDC

192-120148N3 October 2008 33

3.6.7.1 Temperature switch Compax3MP (mains module)

Connector X40 Pin T1R, T2R

Temperature monitoring:

The temperature switch (normally closed contact) must be connected, unless an error message will be issued.

Temperature switch/relay

No galvanic separation, the temperature sensor (normally closed contact) must comply with the safe separation according to EN 60664.

If there is no temperature monitoring due to the connected braking resistor, the T1R and T2R connections must be connected by a jumper.



Caution!

Without temperature monitoring, the braking resistor might be destroyed.

3.6.8. Motor / motor brake Compax3M (axis controller)

Connector X43



| PIN | Designation |
|-----|-----------------------|
| BR+ | Motor holding brake * |
| BR- | Motor holding brake * |
| PE | PE (motor) |
| W | W (motor) |
| V | V (motor) |
| U | U (motor) |

^{*} Please note that Compax3 will report error "open circuit at holding brake" (5481h / 2163d) if the current is below 150mA.

Requirements for Compax3M motor cable

<80m per axis (the cable must not be rolled up!)

The entire length of the motor cable per axis combination may not exceed 300m. A motor output filter is required for motor cables >20m.

- ◆MDR01/04 (max. 6.3A rated motor current)
- ♦ MDR01/01 (max. 16A rated motor current)
- ◆MDR01/02 (max. 30A rated motor current)

Shielding connection of the motor cable

The cable should be fully screened and connected to the Compax3 housing. We offer a special Shield connecting terminal as accessory item (ZBH./...). The shield of the cable must also be connected with the motor housing. The fixing (via plug or screw in the terminal box) depends on the motor type.

Motor cables can be found in the accessories chapter of the device description.

Motor holding brake output

| Motor holding brake output | Compax3 |
|--|------------|
| Voltage range | 21 – 27VDC |
| Maximum output current (short circuit proof) | 1.6A |
| Minimum output current | 150mA |
| Securing of brake Compax3M | 3.15A |



Attention - Wiring of the motor holding brake!

Connect the brake only on motors which have a holding brake! Otherwise make no brake connections at all.

Requirements cables for motor holding brake

If a motor holding brake is present, **a cable** of the motor holding brake must be fed on the device side through the toroidal core ferrite provided as accessory ZBH0x/xx (63Ω @1MHz, di=5.1mm), in order to ensure error-free switching on and off of the motor holding brake.

3.6.8.1 Measurement of the motor temperature of Compax3M (axis controller)

Connector X15

The acquisition of the motor temperature by the axis controller can either take place via the connection of X15 (Tmot) or via the feedback cable and the corresponding connection on X13 PIN10.



| PIN | Description |
|-----|-------------|
| 1 | +5V |
| 2 | Sensor |

The temperature acquisition on X15 Tmot can not be connected at the same time as X13 Pin 10.

192-120148N3 October 2008 35

3.6.9. Safety technology option for Compax3M (axis controller)

Connector X14



| PIN | Description | |
|-----|-------------|--------|
| 1 | STO1/ | +24VDC |
| 2 | STO-GND | GND |
| 3 | STO2/ | +24VDC |
| 4 | STO-GND | GND |



Note!

If the Compax3M axis controller features a safety option, these connections must also be wired, unless it is not possible to set up the axis.

3.7 Communication interfaces

3.7.1. Communikation Compax3M

| In this chapter you can read about: | |
|--|----|
| PC - Compax3MP (mains module) | 37 |
| Communication in the axis combination (connector X30, X31) | 37 |
| Adjusting the basic address | 38 |
| Setting the axis function | 38 |

3.7.1.1 PC - Compax3MP (mains module)

Connector X3



USB2.0

Connect your PC to the USB sleeve X3 of the mains module via an USB cable (SSK33/03).

3.7.1.2 Communication in the axis combination (connector X30, X31)

The communication in the axis combination is implemented via a SSK28 cable and double RJ45 sleeves on the device top.

Beginning with the Compax3MP (mains module) the connection is always made from X30 to X31 of the next device. On the first device (X31) and the last device (X30) in the multi-axis combination, a bus termination plug (BUS07/01) is required.

Orientation to the back



Orientation to the front plate

| , | | |
|------|--------------------------|--|
| | Compax3MP (mains module) | |
| X30 | out | |
| X31 | in | |
| res. | reserved | |
| | | |
| | Compax3M (axis) | |
| X30 | out | |
| X31 | in | |
| res. | reserved | |

Device description Multi-axis devices

3.7.1.3 Adjusting the basic address

On the mains module, the basic address of the device combination is set in steps of 16 with the aid of the first three dip switches.

The mains module contains the set basic address while the axes placed at the right in the combination contain the following addresses.

Switch S1



Address setting

Basic addresses

| Switch | Value upon ON |
|--------|---------------|
| 1 | 16 |
| 2 | 32 |
| 3 | 64 |

Settings:

left: OFF right: ON

Settable value range: 0, 16, 32, 48, 64, 80, 96, 112

Address of the 1st Compax3M = basic address+1

The addresses of the axis controllers are newly assigned after PowerOn.

Example:

Basic address = 48; mains module with 6 Compax3M axes in the combination.

1. Axis right: Address = 49 2. Axis right: Address = 50

...

6. Axis right: Address = 54

3.7.1.4 Setting the axis function

Switch S10



Function settings for T30 and T40

The value of switch S10 on the axis controller is stored in object O110.1 C3plus.Switch_DeviceFunction and can be evaluated with the aid of a program. This helps realize a more simple function selection.

3.8 Signal interfaces

| In this chapter you can read about: | |
|-------------------------------------|----|
| Resolver / Feedback (connector X13) | 39 |
| Analog / Encoder (plug X11) | |
| Digital inputs/outputs (plug X12) | 41 |

3.8.1. Resolver / feedback (connector X13)



| PIN X13 | Feedback /X13 High Density /Sub D (depending on the Feedback module) | | | |
|---------|--|------------------------------|-----------------------------|--|
| | Resolver (F10) | SinCos (F11) | EnDat 2.1 (F12) | |
| 1 | Reserved | Reserved | Sense -* | |
| 2 | Reserved | Reserved | Sense +* | |
| 3 | GND | GND | Reserved | |
| 4 | REF-Resolver+ | Vcc (+8V) | Vcc (+5V) * max. 350mA load | |
| 5 | +5V (for temperature | +5V (for temperature sensor) | | |
| 6 | Reserved | Reserved | CLKfbk | |
| 7 | SIN- | SIN- | SIN- / A- (Encoder) | |
| 8 | SIN+ | SIN+ | SIN+ / A+ (Encoder) | |
| 9 | Reserved | Reserved | CLKfbk/ | |
| 10 | Tmot* | Tmot* | Tmot* | |
| 11 | COS- | COS- | COS- / B- (Encoder) | |
| 12 | COS+ | COS+ | COS+ / B+ (Encoder) | |
| 13 | Reserved | DATAfbk | DATAfbk | |
| 14 | Reserved | DATAfbk/ | DATAfbk/ | |
| 15 | REF-Resolver- | GND (Vcc) | GND (Vcc) | |

^{*}X13 Pin10 Tmot may not be connected at the same time as X15 (on Compaxx3M).

Resolver cables can be found in the accessories chapter of the device description. SinCos[®] - cables can be found in the accessories chapter of the device description. The EnDat cable GBK38 can be found in the accessories chapter of the device description.

| PIN X13 | Feedback /X13 High Density /Sub D |
|---------|---|
| | Direct drives (F12) |
| 1 | Sense -* |
| 2 | Sense +* |
| 3 | Hall1 (digital) |
| 4 | Vcc (+5V) * max. 350mA load |
| 5 | +5V (for temperature- and hall-sensors) |
| 6 | Hall2 (digital) |
| 7 | SIN-, A- (Encoder) or analog Hall sensor |
| 8 | SIN+, A+, (Encoder) or analog Hall sensor |
| 9 | Hall3 (digital) |
| 10 | Tmot* |
| 11 | COS-, B- (Encoder) or analog Hall sensor |
| 12 | COS+, B+ (Encoder) or analog Hall sensor |
| 13 | N+ |
| 14 | N- |
| 15 | GND (Vcc) |

^{*}X13 Pin10 Tmot may not be connected at the same time as X15 (on Compaxx3M).

Note on F12:

*+5V (Pin 4) is measured and controlled directly at the end of the line via Sense – and Sense +.

Maximum cable length: 100m

Caution!

- ◆ Pin 4 and Pin 5 must under no circumstances be connected!
- ◆ Plug in or pull out feedback connector only in switched off state (24VDC switched off).

Device description Multi-axis devices

3.8.2. Analog / Encoder (plug X11)



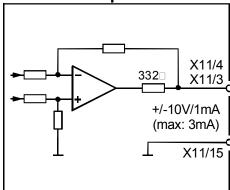
| PIN X11 | Reference | | |
|---------|---|---|--------|
| | High Density Sub D | _ | |
| | | Encoders | SSI |
| 1 | +24V (output) max. 70mA | | |
| 2 | Ain1 -: analog input - (14Bit; max. +/-10V) | | |
| 3 | D/A monitor channel 1 (±10V, 8-bit resolut | ion) | |
| 4 | D/A monitor channel 0 (±10V, 8-bit resolut | ion) | |
| 5 | +5V (output for encoder) max. 150mA | | |
| 6 | - Input: steps RS422 (5V - level) | A/ (Input / simulation) | Clock- |
| 7 | + Input: steps RS422 (5V - level) | A (Input / simulation) | Clock+ |
| 8 | + Input: direction RS422 (5V - level) | B (Input / simulation) | |
| 9 | Ain0 +: analog input + (14Bit; max. +/-10V) | | |
| 10 | Ain1 +: analog input + (14Bit; max. +/-10V | Ain1 +: analog input + (14Bit; max. +/-10V) | |
| 11 | Ain0 -: analog input - (14Bit; max. +/-10V) | | |
| 12 | - Input: direction RS422 (5V - level) | B/ (Input / simulation) | |
| 13 | Reserved | N/ (Input / simulation) | DATA- |
| 14 | Reserved | N (Input / simulation) | DATA+ |
| 15 | GND | | |

Technical data X11 (see on page 46)

3.8.2.1 Wiring of analog interfaces

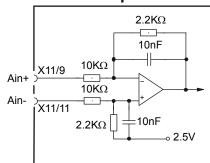
Output

Compax3



Input

Compax3

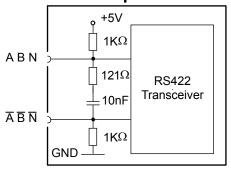


Please note: with Ain- on earth and Ain+ open, 2.02V are read in.

Structure image of the internal signal processing of the analog inputs Ain1 (X11/10 and X11/2) has the same wiring!

3.8.2.2 Connections of the encoder interface

Compax3



The input connection is available in triple (for A & /A, B & /B, N & /N)

Parker EME Device description

3.8.3. Digital inputs/outputs (plug X12)



| Pin X12 | Input/output | I/O /X12 High density/Sub D |
|---------|--------------|---|
| 1 | Output | +24VDC output (max. 340mA) |
| 2 | O0 | Output 0 (max. 100mA) |
| 3 | 01 | Output 1 (max. 100mA) |
| 4 | O2 | Output 2 (max. 100mA) |
| 5 | O3 | Output 3 (max. 100mA) |
| 6 | 10 | Input 0 |
| 7 | I1 | Input 1 |
| 8 | 12 | Input 2 |
| 9 | 13 | Input 3 |
| 10 | 14 | Input 4 |
| 11 | I | 24V input for the digital outputs Pins 2 to 5 |
| 12 | 15 | Input 5 |
| 13 | 16 | Input 6 |
| 14 | 17 | Input 7 |
| 15 | Output | Gnd 24 V |

All inputs and outputs have 24V level.

The exact assignment depends on the the device type!

You will find the description of the device-specific assignment in the online help which can be opened from the Compax3 – ServoManager.

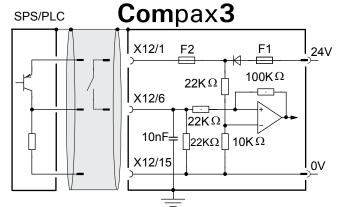
Maximum capacitive loading of the outputs: 30nF (max. 2 Compax3 inputs).

3.8.3.1 Connection of the digital Outputs/Inputs

Wiring of digital outputs

The circuit example is valid for all digital outputs! The outputs are short circuit proof; a short circuit generates an error.

Status of digital inputs



The circuit example is valid for all digital inputs! Signal level:

- \Rightarrow 9.15V = "1" (38,2% of the control voltage applied)
- > 8.05V = "0" (33.5% of the control voltage applied)

F1: delayed action fuse

F2: quick action electronic fuse; can be reset by switching the 24VDC supply off and on again.

Technical data Multi-axis devices

4. Technical data

Size / weight of Compax3MP/Compax3M

| Device type | Dimensions HxWxD [mm] | Weight [kg] |
|---------------|-----------------------|----------------|
| Compax3MP10D6 | 360 x 50 x 263 | 3.95 |
| Compax3MP20D6 | 360 x 100 x 263 | 6.3 |
| Compax3M050D6 | 360 x 50 x 263 | 3.5 |
| Compax3M100D6 | 360 x 50 x 263 | 3.6 |
| Compax3M150D6 | 360 x 50 x 263 | 3.6 |
| Compax3M300D6 | 360 x 100 x 263 | 5.25 |

Protection type IP20

Mains connection Compax3MP10D6

| Device type Compax3MP10 | 230V | 400V | 480V |
|--|---|------------------------|------------------------|
| Supply voltage | 230VAC ±10% 50-60Hz | 400VAC ±10% 50-60Hz | 480VAC ±10% 50-60Hz |
| Rated voltage | 3AC 230V | 3AC 400V | 3AC 480V |
| Input current | 22Aeff | 22Aeff | 18Arms |
| Output voltage | 325VDC ±10% | 565VDC ±10% | 680VDC ±10% |
| Output power | 6kW 10 kW 10 kW | | |
| | Measure for line and device protection: | | |
| Maximum fuse rating per device (=short circuit rating) | MCB miniature circuit breaker 25A according to UL category DIVQ Recommendation: (ABB) S203UP-K 25(480VAC) | | |

Mains connection Compax3MP20D6

| Device type Compax3MP20 | 230V | 400V | 480V |
|--|---|------------------------|------------------------|
| Supply voltage | 230VAC ±10% 50-60Hz | 400VAC ±10% 50-60Hz | 480VAC ±10% 50-60Hz |
| Rated voltage | 3AC 230V | 3AC 400V | 3AC 480V |
| Input current | 44Arms | 44Arms | 35Arms |
| Output voltage | 325VDC ±10% | 565VDC ±10% | 680VDC ±10% |
| Output power | 12kW | 20kW | 20kW |
| Maximum fuse rating per device (=short circuit rating) 2 circuit breakers in line are required | Measure for line protection: MCB with a rating of 50A / 4xxVAC (depending on the input voltage)Recommendation: Recommendation: (ABB) S203U-K50 (440VAC) Measure for device protection: | | |
| | Fuses 80A / 660VAC per supply leg according to UL category JFHR2 Bussmann 170M1366, 170M1566D | | |

Control voltage 24VDC Compax3MP / Compax3M

| Device type | Compax3MP / Compax3M |
|--|--|
| Voltage range | 21 - 27VDC |
| Mains module | with switch-on current limitation, due to capacitive load |
| Fuse | MCB miniature circuit breaker or "delayed action fuse", due to capacitive load |
| Current drain of the device | C3MP10D6: 0,2A C3MP20D6: 0.3A |
| Total current drain | C3M050D6: 0,85A C3M100D6: 0.85A C3M150D6: 0.85A C3M300D6: 1.0 A + Total load of the digital outputs + current for the motor holding brake |
| Ripple | 0.5Vpp |
| Requirement according to safe extra low voltage (SELV) | yes |
| Short-circuit proof | conditional (each device internally protected with 3.15AT) |

Output data Compax3Mxxx at 3*230VAC

| Device type Compax3 | M050D6 | M100D6 | M150D6 | M300D6 |
|------------------------|--------------|--------------------|---------|---------|
| Power Input | 325VDC ±10% | | | |
| Output voltage | 3x 0-230V (0 | 3x 0-230V (0500Hz) | | |
| Nominal output current | 5Aeff | 10Aeff | 15Aeff | 30Aeff |
| Pulse current for 5s * | 10Aeff | 20Aeff | 30Aeff | 60Aeff |
| Power | 2kVA | 4kVA | 6kVA | 12kVA |
| Switching frequency | 8kHz | 8kHz | 8kHz | 8kHz |
| Power loss for In | 70W+** | 90W+** | 120W+** | 270W+** |

^{*}Turning frequency for pulse current: f>5Hz

Output data Compax3Mxxx at 3*400VAC

| Device type Compax3 | M050D6 | M100D6 | M150D6 | M300D6 |
|------------------------|--------------|--------------------|---------|---------|
| Power Input | 565VDC ±10 | 565VDC ±10% | | |
| Output voltage | 3x 0-400V (0 | 3x 0-400V (0500Hz) | | |
| Nominal output current | 5Aeff | 10Aeff | 15Aeff | 30Aeff |
| Pulse current for 5s * | 10Aeff | 20Aeff | 30Aeff | 60Aeff |
| Power | 3.33kVA | 6.66kVA | 10kVA | 20kVA |
| Switching frequency | 8kHz | 8kHz | 8kHz | 8kHz |
| Power loss for In | 70W+** | 90W+** | 120W+** | 270W+** |

^{*}Turning frequency for pulse current: f>5Hz

^{**} Maximum additinal losses with option card 5W.

^{**} Maximum additinal losses with option card 5W.

Technical data Multi-axis devices

Output data Compax3Mxxx at 3*480VAC

| Device type Compax3 | M050D6 | M100D6 | M150D6 | M300D6 |
|------------------------|--------------|--------------------|----------|---------|
| Power Input | 680VDC ±10 | 680VDC ±10% | | |
| Output voltage | 3x 0-480V (0 | 3x 0-480V (0500Hz) | | |
| Nominal output current | 4Aeff | 8Arms | 12.5Arms | 25Arms |
| Pulse current for 5s * | 8Arms | 16Arms | 25Arms | 50Arms |
| Power | 3.33kVA | 6.66kVA | 10kVA | 20kVA |
| Switching frequency | 8kHz | 8kHz | 8kHz | 8kHz |
| Power loss for In | 70W+** | 90W+** | 120W+** | 270W+** |

^{*}Turning frequency for pulse current: f>5Hz

Resolution of the motor position

| For option F10: Resolver | ◆Position resolution: 16 Bit (= 0.005°) |
|-------------------------------------|--|
| Feedback | ♦ Absolute accuracy: ±0,167° |
| For option F11: SinCos [©] | ◆ Position resolution: 13.5Bit/Encoder sine period => 0.03107°/encoder resolution |
| For option F12: | ◆ Maximum position resolution |
| | Linear: 24 Bits per motor magnet spacing Rotary: 24 bits per motor revolution |
| | ◆For 1Vss sine-cosine encoders (e.g. EnDat): 13.5 bits / graduation of the scale of the encoder |
| | ◆For RS 422 encoders: 4x encoder resolution |
| | ◆Accuracy of the feedback zero pulse acquisition = accuracy of the feedback resolution |
| | ◆Resolution for analog hall sensors with 1Vss signal: 13.5 bits / motor magnet spacing |

Accuracy

The exactitude of the position signal is above all determined by the exactitude of the feedback system used.

^{**} Maximum additinal losses with option card 5W.

Parker EME Technical data

Motors and feedback systems supported

| Motors Direct drives | ◆Sinusoidal commutated synchronous motors |
|----------------------|---|
| ◆Linear motors | Maximum rotating field frequency: 1,000Hz |
| ◆Torque motors | Max. velocity at 8 pole motors: 15000min-1. |
| ' | ◆ General max. speed: 60*1000/number of pole pairs in [min⁻¹]. |
| | Max. number of poles = 600 |
| | ◆ Sinusoidal commutated asynchronous motors |
| | ◆ Maximum rotating field frequency: 1,000Hz |
| | Max. speed: 60*1000/number of pole pairs - slip in [min⁻¹)]. |
| | Field suppression: typically up to triple (higher on request). |
| | ◆ Temperature sensor: KTY84-130 (insulated according to EN60664-1 or IEC60664-1) |
| | ♦3 phase synchronous direct drives |
| Position encoder | |
| (Feedback) | Option F10: Resolver Feedback |
| LTN: | ◆ JSSBH-15-E-5 |
| | ◆JSSBH-21-P4 |
| | ◆RE-21-1-A05 |
| | ◆RE-15-1-B04 |
| Tamagawa: | ◆2018N321 E64 |
| Siemens: | ◆23401-T2509-C202 |
| | |
| | Option F11: SinCos® |
| | ◆ Singleturn (SICK Stegmann) |
| | ◆ Multiturn (SICK Stegmann) Absolute position up to 4096 motor revolutions. |
| | ◆Rotary feedback with HIPERFACE® interface: For example: SRS50, SRM50, SKS36, SKM36, SEK52 |

Technical data Multi-axis devices

| Special encoder systems for direct drives | Option F12 |
|---|---|
| Analog hall sensors | ◆ Sine - Cosine signal (max. 5Vss*; typical 1Vss) 90° offset |
| | ◆U-V signal (max. 5Vss*; typical 1Vss) 120° offset. |
| Encoder (linear or rotatory) | ◆ Sine-cosine (max. 5Vss*; typical 1Vss) (max. 400kHz) or |
| | ◆TTL (RS422) (max. 5MHz) |
| | with the following modes of commutation: |
| | ◆ Automatic commutation or |
| | ◆ Digital hall sensors (e.g. DiCoder [©]) |
| Digital, bidirectional interface | ◆ All EnDat 2.1 or EnDat 2.2 feedback systems with incremental track (sinecosine track) |
| | ♦ linear or rotary |
| | ◆ max. 400kHz Sine-Cosine |
| Distance coded feedback systems | ◆ Distance coding with 1VSS - Interface |
| | ◆ Distance coding with RS422 - Interface (Encoder) |

^{*}Max. differential input between SIN- (X13/7) and SIN+ (X13/8).

Motor holding brake output

| Motor holding brake output | Compax3 |
|--|------------|
| Voltage range | 21 – 27VDC |
| Maximum output current (short circuit proof) | 1.6A |
| Minimum output current | 150mA |
| Securing of brake Compax3M | 3.15A |

Safety technology Compax3MP / Compax3M

| Safety technology as an option State-of-the-art EN ISO 13849 | ◆ Please respect the stated safety technology on the type designation plate (see on page 8) and the circuitry examples |
|--|---|
|--|---|

UL certifiction for Compax3M

| conform to UL: | ◆according to UL508C |
|----------------|-----------------------|
| Certified | ◆E-File_No.: E235 342 |

The UL certification is documented by a "UL" logo on the device (type specification plate).



Insulation requirements

| Protection class | Protection class I according to EN 60664-1 |
|--|--|
| Protection against human contact with dangerous voltages | According to |
| Overvoltage category | Voltage class III according to EN 60664-1 |
| Pollution degree | Degree of contamination 2 according |

Environmnental conditions Compax3MP / Compax3M

| General ambient conditions Permissible ambient temperature: | In accordance with EN 60 721-3-1 to 3-3 Climate (temperature/humidity/barometric pressure): Class 3K3 | |
|--|---|-----|
| Operation Storage Transport | 0 to +40 °C Class -25 to +70 °C -25 to +70 °C | 3K3 |
| Tolerated humidity: | No condensation | |
| Operation Storage Transport | <= 85% class 3K3 <= 95% <= 95% | |
| Elevation of operating site | <=1000m above sea level for 100% load ratings <=2000m above sea level for 1% / 100m power reduction Please inquire for greater elevations | |
| Sealing | IP20 protection class according to EN 60 529 | |
| Mechanic resonances: | Class 2M3, 20m/s ² ;8-200Hz | |

Cooling Compax3MP / Compax3M

| Cooling mode: | Forced air ventilation with fan in the heat |
|---------------|---|
| | dissipator |

EMC limit values Compax3MP/Compax3M

| EMC interference emission | Limit values according to EN 61 800-3, Limit value class C3 with mains filter. |
|---------------------------|---|
| EMC disturbance immunity | Industrial area limit values in accordance with EN 61 800-3 |

EC directives and harmonised EC norms

| EC low voltage directive 2006/95/EG | EN 61800-5-1, Standard for electric power drives with settable speed; requirements to electric safety |
|-------------------------------------|---|
| | EN 60664-1 , isolation coordinates for electricale equipment in low-voltage systems |
| | EN 60 204-1, Machinery norm, partly applied |
| EC-EMC directive 2004/108/EG | EN 61 800-3, EMC norm |
| | Product standard for variable speed drives |

Detailed information on the technical data of the Compax3 devices can be found in the Help- or PDF-files of the individual Compax3 device types.

Index Multi-axis devices

5. Index

| A | Meaning of the status LEDs - Compax3 axis controller • 24 |
|---|---|
| Adjusting the basic address • 38 | Meaning of the status LEDs - Compax3MP |
| Analog / Encoder (plug X11) • 40 | (mains module) • 25 Measurement of the motor temperature of |
| В | Compax3M (axis controller) • 35 Motor / motor brake Compax3M (axis |
| Braking resistor / temperature switch Compax3MP (mains module) • 33 | controller) • 34 Mounting and dimensions • 22 |
| C | Mounting and dimensions |
| C3 ServoManager • 4 | Compax3MP10/M050-150 • 22 |
| Communication in the axis combination | N |
| (connector X30, X31) • 37 Communication interfaces • 37 | Notes on the Documents Supplied • 3 |
| Communikation Compax3M • 37 | P |
| Compax3MP/Compax3M connections • 26 | Deckaring transport starage - 10 |
| Conditions of utilization • 14 | Packaging, transport, storage • 10 PC - Compax3MP (mains module) • 37 |
| Conditions of utilization for CE-conform operation • 14 | Plug assignment Compax3S0xx V2 • 39 |
| Conditions of utilization for UL certification Compax3M • 16 | R |
| Connection of the digital Outputs/Inputs • 42 | Resolver / Feedback (connector X13) • 39 |
| Connections of the axis combination • 28 | Resolver Feedback • 39 |
| Connections of the encoder interface • 41 Connections on the device bottom • 27 | S |
| Connector and pin assignment • 29 | Cofety Instructions - 11 |
| Control voltage 24VDC Compax3MP (mains | Safety Instructions • 11 Safety technology option for Compax3M (axis |
| module) • 31 | controller) • 36 |
| Current on the mains PE (leakage current) • 17 | Safety-conscious working • 11 |
| D | Setting the axis function • 38 |
| Designated use • 11 | Signal interfaces • 39 Special safety instructions • 12 |
| Device assignment • 7 | State of delivery • 24 |
| Device description • 20 | Status LEDs • 24, 25 |
| Digital inputs/outputs • 42 | Supply networks • 18 |
| Digital inputs/outputs (plug X12) • 41 | Т |
| F | Technical data • 43 |
| Front connector • 26 | Temperature switch Compax3MP (mains |
| G | module) • 34 Type specification plate • 8 |
| General hazards • 11 | W |
| 1 | Warranty conditions • 13 |
| Installation and dimensions | Wiring of analog interfaces • 41 |
| Compax3MP20/M300 • 23 | With upper mounting, the housing design may be different |
| Installation instructions Compax3M • 20 | 24 |
| Introduction • 7 | X |
| L | X11 • 40 |
| LEDs • 24, 25 | X12 • 41 |
| Level • 42 | X13 • 39 |
| M | |
| Mains supply Compax3MP (mains module) • | |

48 192-120148N3 October 2008

Manufacturer's Declaration of Conformity • 19